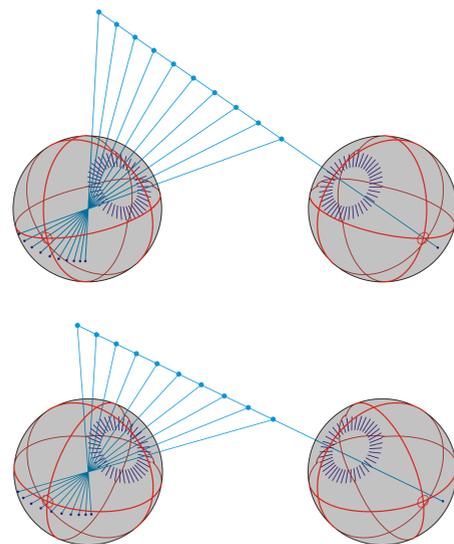
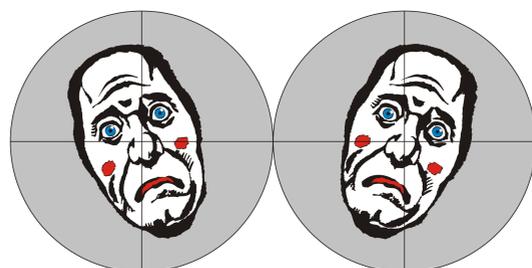


INTRODUCTION

- To achieve stereopsis, the brain must search for matching images on the two retinas—a complex task.
- Geometry restricts the matches to epipolar lines; if the brain could locate these lines, its search would be simplified.
- But epipolar lines move on the retinas when the eyes move, so locating them would require the brain to keep track of eye position.



- Stereopsis can work without *motor* or *proprioceptive* information about eye position.
- But the retinal images themselves contain eye-position information; e.g. if the images are cyclorotated, the eyes must be cycloverged.

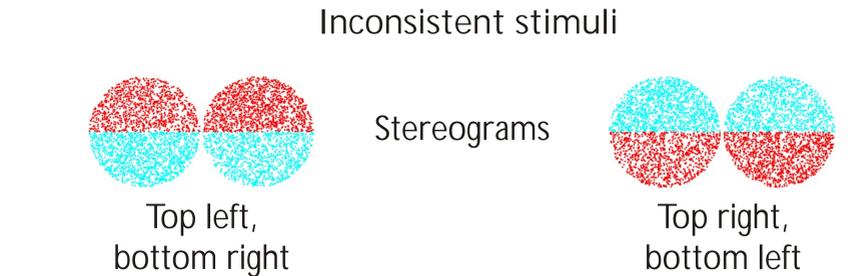
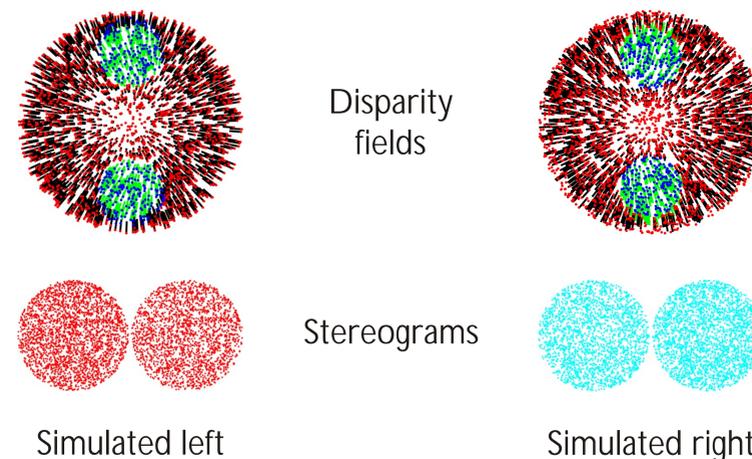
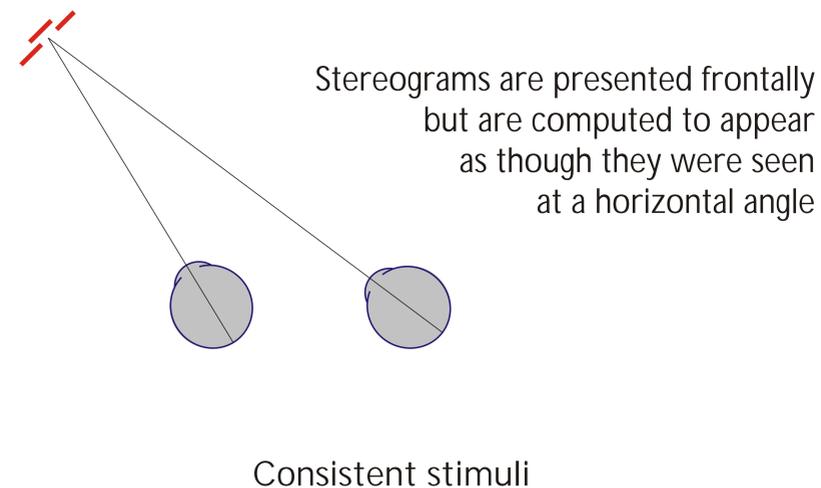


QUESTION

- Does the brain use ‘visual bootstrapping’: does it use a few matched elements to compute eye position so as to speed the search for other matches?

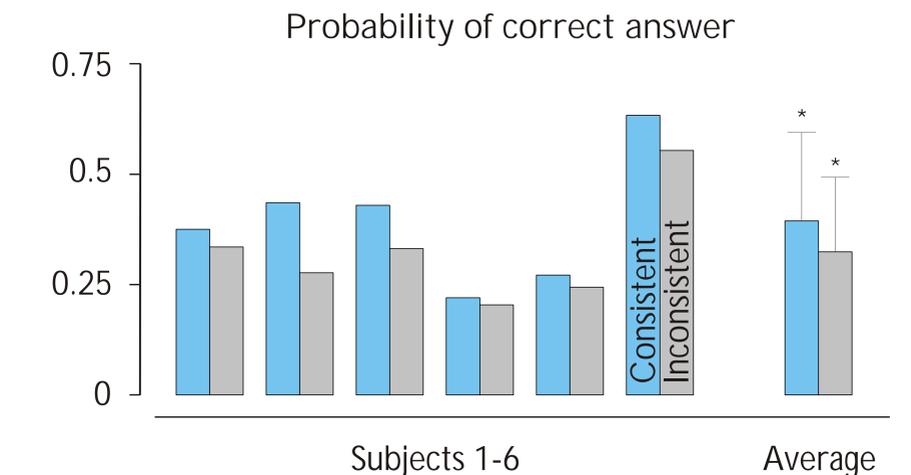
METHODS

- If matching works by bootstrapping, we should have trouble seeing ‘impossible’ stereograms that contain contradictory information about eye position.



RESULTS

- Stereopsis is worse ($p < 0.05$) when the image allows no consistent computation of eye position.



CONCLUSIONS

- The brain uses visual information about eye position to help stereopsis.
- Most likely it computes an estimate of eye position that constrains stereo matching.
- Matching is influenced by image geometry on remote parts of the retina, i.e. there is one global estimate of eye position, not separate estimates for different parts of the image.